

Fisher L2e™ Electric Level Controller

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Figure 1. Fisher L2e Electric Level Controller



Introduction

Scope of Manual

This instruction manual includes installation, adjustment, maintenance, and parts ordering information for the Fisher L2e electric liquid level controller.

Do not install, operate or maintain an L2e electric liquid level controller without being fully trained and qualified in valve, actuator, and accessory installation, operation, and maintenance. To avoid personal injury or property damage, it is important to carefully read, understand and follow all the contents of this manual, including all safety cautions and warnings. If you have any questions about these instructions, contact your [Emerson Process Management sales office](#) before proceeding.



Description

The L2e electric liquid level differential gap on-off controller uses a displacement type sensor to detect liquid level or the interface of two liquids of different specific gravities.

The L2e controls the lower trip point (zero) that closes the dump valve, allowing the vessel to fill to the upper trip point. Once the upper trip point is reached, the dump valve opens to drain the fluid down to the zero or lower trip point. The difference between the upper trip point and the zero or lower trip point is called differential gap or DG. The L2e operates as a two position (on-off) controller.

These controllers use a single pole double throw (SPDT) dry contact electric switch to provide differential gap (DG) control or liquid monitoring. The controller can be used to provide an electric control signal to an electrically actuated control valve.

Unless otherwise noted, all NACE references are to NACE MR0175-2002.

Specifications

Specifications for the controller and sensor are listed in table 1.

Educational Services

For information on available courses for L2e electric liquid level controllers, as well as a variety of other products, contact:

Emerson Process Management
Educational Services - Registration
Phone: +1-641-754-3771 or +1-800-338-8158
Email: education@emerson.com
<http://www.emersonprocess.com/education>



Table 1. Specifications

<p>Available Configurations</p> <p>Controller: Differential gap (DG) electric control action with intuitive Zero and Span Adjustments in SPDT dry contact configuration (refer to page 2 for differential gap description)</p> <p>Sensor: Displacer-type liquid level sensor for mounting to side of vessel</p> <p>Input Signal</p> <p>Type: Liquid level or liquid-to-liquid interface</p> <p>Level Change Required for Full Change in State of Output: 5.0 to 559 mm (0.2 to 22 inches)</p> <p>Vessel level DG is dependant on factors such as valve sizing, actuator speed, rate, liquid out flow, and vessel size. Contact your Emerson Process Management sales office for Fisher Electric Level Loop performance optimization.</p> <p>Specific Gravity Limits</p> <p>Minimum SG: 0.15</p> <p>Maximum SG</p> <p>PVC Displacer: 1.3</p> <p>SST Displacer: 1.1</p> <p>Electrical Rating (Output)</p> <ul style="list-style-type: none"> ■ easy-Drive™ actuator application: 7 mA@5 VDC ■ Other applications: 1 amp resistive, 0.5 amp inductive/28 VDC <p>Note: Use with easy-Drive after first being used in other high power application is not recommended.</p> <p>Power Consumption</p> <p>Switch consumes no power to operate, so it has no current leakage or voltage drop</p> <p>Sensor to Vessel Connection</p> <ul style="list-style-type: none"> ■ 2 NPT threaded or ■ NPS 2 CL150 through 1500 slip-on flange connection⁽¹⁾ <p>Controller Connection</p> <p>Electrical 1/2-14 NPT external conduit connection with 18 inches of 18 AWG lead wires, located at the bottom of the case</p>	<p>Displacer Sizes</p> <ul style="list-style-type: none"> ■ 48 X 305 mm, 541 cm³ (1-7/8 X 12 inches, 33 in³) ■ 76 X 152 mm, 688 cm³ (3 X 6 inches, 42 in³) <p>Maximum Displacer Insertion Length⁽²⁾, Horizontal or Vertical</p> <p>1-7/8 x 12 Displacer with one 6-inch extension (optional use)</p> <p>3 x 6 Displacer with one 3-inch extension (optional use)</p> <p>Displacer Material and Maximum Sensor Working Pressure⁽³⁾</p> <p>PVC Displacer: Consistent with CL1500 pressure temperature ratings per ASME B16.34 up to maximum pressure of 258.5 bar (3750 psig). For PED (97/23/EC) maximum pressure limited to 200 bar (2900 psig).</p> <p>S31603 SST Displacer: CL600 pressure temperature ratings per ASME B16.34 up to maximum pressure of 99.3 bar (1440 psig)</p> <p>Note: For slip-on flange connection, maximum sensor working pressure must be consistent with the flange ratings</p> <p>Operative Ambient Temperature Limits⁽³⁾</p> <p>Controller: -40 to 75°C (-40 to 167°F)</p> <p>Operative Process Temperature Limits⁽³⁾</p> <p>Sensor:</p> <ul style="list-style-type: none"> ■ PVC Displacer: -18 to 71°C (0 to 160°F) ■ S31603 SST Displacer: -40 to 204°C (-40 to 400°F) <p>Construction Materials</p> <p>Controller</p> <p>Case and Cover: Marine grade aluminum</p> <p>Switch: Stainless steel</p> <p>Span Levers: Stainless steel</p> <p>Springs: Stainless steel</p> <p>Sensor</p> <p>Sensor Body: LCC</p> <p>O-Rings: Fluorocarbon</p> <p>Pivot Assembly: Stainless steel</p> <p>Displacer: ■ Polyvinylchloride (PVC) or ■ S31603 SST</p> <p>Sensor Spring: Stainless steel</p>
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-continued-

Table 1. Specifications (continued)

<p>Hazardous Area Classifications Available</p> <p>Switch Only</p> <p>cCSAus Explosion-proof Class I Division 1, Groups ABCD Dust Ignition-proof Class II Division 1, Groups EFG Dual Seal</p> <p>ATEX ⓂII 2 GD Flameproof Ex d IIC T6 (Ta=-40°C to + 75°C) Dust Ex tb IIIC T85°C Db IP6X (Ta = -40° to +75°C) 1 A Max</p> <p>IECEX Flameproof Ex d IIC T6 (Ta=-40°C to + 75°C) Dust Ex tb IIIC T85°C Db IP6X (Ta = -40° to +75°C) 1 A Max</p>	<p>Canadian Registration (CRN)</p> <p>The L2e utilizes the same sensor unit pressure component as the L2 pneumatic controller version. Refer to the L2 CRN which is deemed applicable to the L2e.</p> <p>Declaration of SEP</p> <p>Fisher Controls International LLC declares this product to be in compliance with Article 3 paragraph 3 of the Pressure Equipment Directive (PED) 97 / 23 / EC. It was designed and manufactured in accordance with Sound Engineering Practice (SEP) and cannot bear the CE marking related to PED compliance. However, the product may bear the CE marking to indicate compliance with other applicable European Community Directives.</p>
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NOTE: Specialized instrument terms are defined in ANSI/ISA Standard 51.1 - Process Instrument Terminology.

1. Converting from a threaded NPT connection to a flange connection is to be done by the end-user. Refer to [Converting a Threaded NPT Connection to a Flange Connection instruction Manual Supplement \(D103277X012\)](#), available at www.Fisher.com or from your [Emerson Process Management sales office](#).

2. Maximum span setting with 1 7/8 x 12 inch horizontal displacer plus 6 inch extension is not recommended due to potentially insufficient zero adjustment.

3. The pressure and temperature limits in this document and any applicable code limitations should not be exceeded.

Installation

⚠ WARNING

Always wear protective clothing, gloves, and eyewear when performing any installation operations to avoid personal injury.

To avoid personal injury or property damage caused by the sudden release of process fluid, be certain the service conditions do not exceed the sensor pressure limits. Use pressure-limiting or pressure-relieving devices to prevent service conditions from exceeding these limits.

Check with your process or safety engineer for any additional measures that must be taken to protect against process media.

If installing this into an existing application, also refer to the WARNING at the beginning of the Maintenance section of this instruction manual.

CAUTION

If the L2e electric level controller is installed on a vessel that is to be shipped to a different location (e.g. skid mounted units), remove the displacer and displacer rod extensions before shipment. Failure to do so could result in damage to the instrument and/or the displacer rod due to vibration and impact loading during shipment. After the vessel is installed at its final location, reassemble the displacer and displacer rod extension.

Note

Use with easy-Drive electric actuator after first being used in other high power application is not recommended.

1. Be sure there are no obstructions inside the vessel that will interfere with displacer installation or operation.
2. Provide the appropriate connection in the vessel wall to match the sensor connection. Locate the vessel wall connection such that the displacer will be at the desired control level.

Attaching a Vertical Displacer

Refer to figure 9 for part locations.

1. Thread jam nut (key 63) all the way onto the threaded portion of the universal joint assembly (key 69).
2. Thread the displacer (key 81) all the way onto the threaded portion of the universal joint assembly.
3. Tighten the jam nut against the displacer.

Attaching a Horizontal Displacer

Refer to figure 9 for part locations.

1. Thread the displacer (key 81) all the way onto the displacer rod (key 64) or extension (key 82) and tighten.

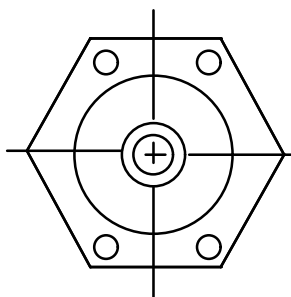
Attaching the Sensor to the Vessel

Insert the displacer end of the L2e sensor into the vessel connection and tighten enough to seal the threads. If necessary, loosen or tighten slightly to obtain the horizontal orientation shown in figure 2. Make sure that the controller case is level.

CAUTION

The displacer rod (key 64) is not a handle. Grasp sensor body or controller housing to lift and carry to avoid internal component damage.

Figure 2. Sensor Orientation



**CORRECT CONTROLLER MOUNTING
HOLE ORIENTATION WHEN MOUNTED ON VESSEL**

Electrical Connections

⚠ WARNING

For explosion-proof applications, disconnect power before installing, servicing or removing electrical components. Personal injury or property damage from fire or explosion may result if power is not disconnected.

Select junction boxes, wiring and/or cable glands that are rated for the environment of use (such as hazardous location, ingress protection, and temperature). Failure to use properly rated electrical hardware wiring and/or cable glands can result in personal injury or property damage from fire or explosion. Wiring connections must be in accordance with local, regional, and national codes for any given hazardous area approval. Failure to follow the local, regional, and national codes could result in personal injury or property damage from fire or explosion.

An electrical 1/2-14 NPT conduit connection with 18 inches of 18 AWG lead wires is located at the bottom of the case. The conduit connection is integral to the body of the switch.

The action of the controller is such that rising level will cause the Normally Closed (N/C) contacts to close and the Normally Open (N/O) contacts to open. Falling level causes the opposite action.

Connect L2e electrical wires as shown in table 2. To reverse the action refer to table 2 and reverse wiring for normally open and normally closed.

Table 2. L2e Electrical Wire Configuration

Wire Color	SPDT Action
Red	Normally Closed
Brown	Common
Blue	Normally Open
Green	Ground

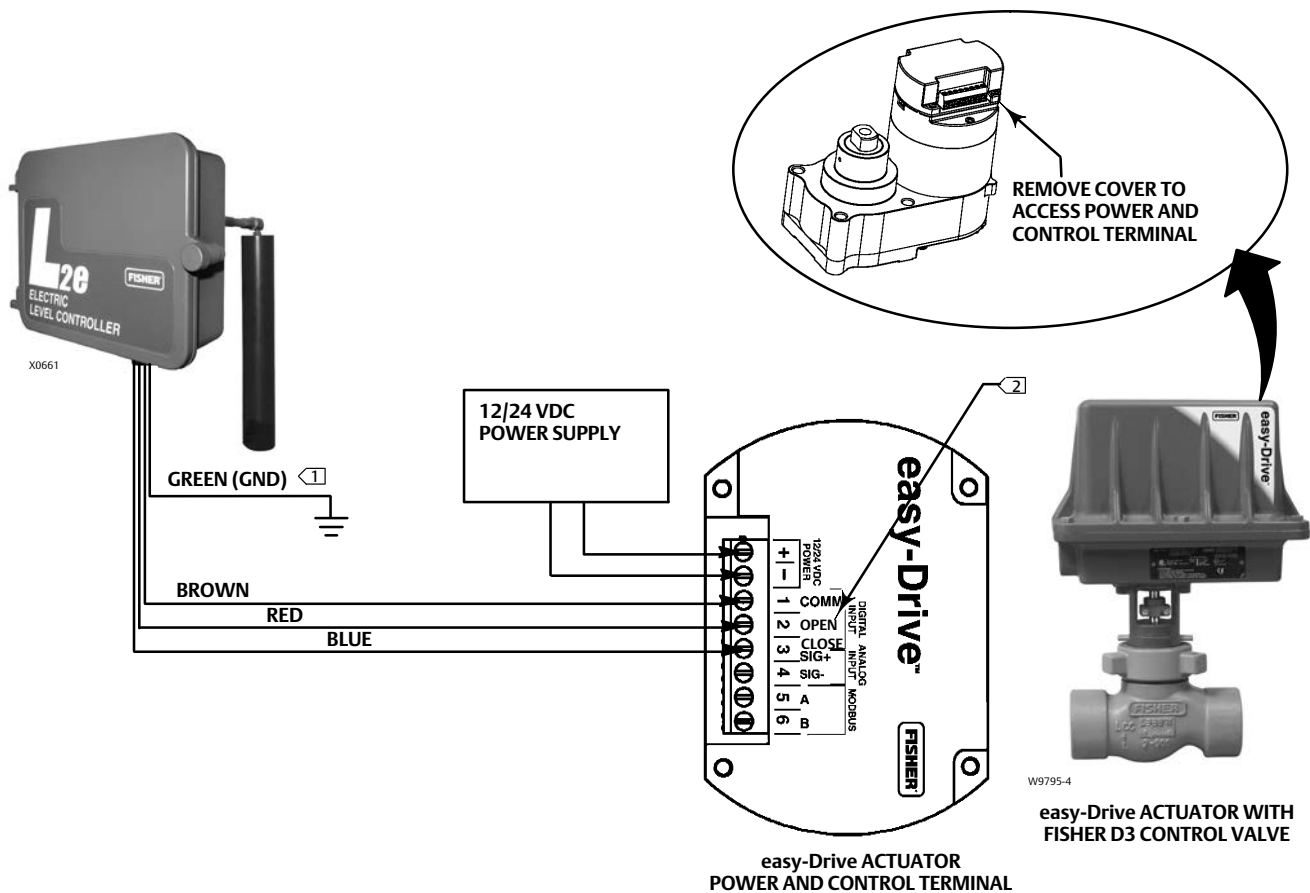
Wiring Configurations

There are two recommended wiring configurations depending on the preferred site solution and approach to electric level control; a direct connection to the easy-Drive actuator, shown in figure 3 or a direct connection to the easy-Drive actuator and a remote monitor (figure 4 and 5). In these examples, the L2e is wired using a common and separate N/O or N/C contact. When implemented as suggested, these wiring configurations provide definitive level switch points and help reduce issues associated with single pole single throw contact switches, such as “bouncing” due to vibration or sloshing liquids in a vessel.

Note

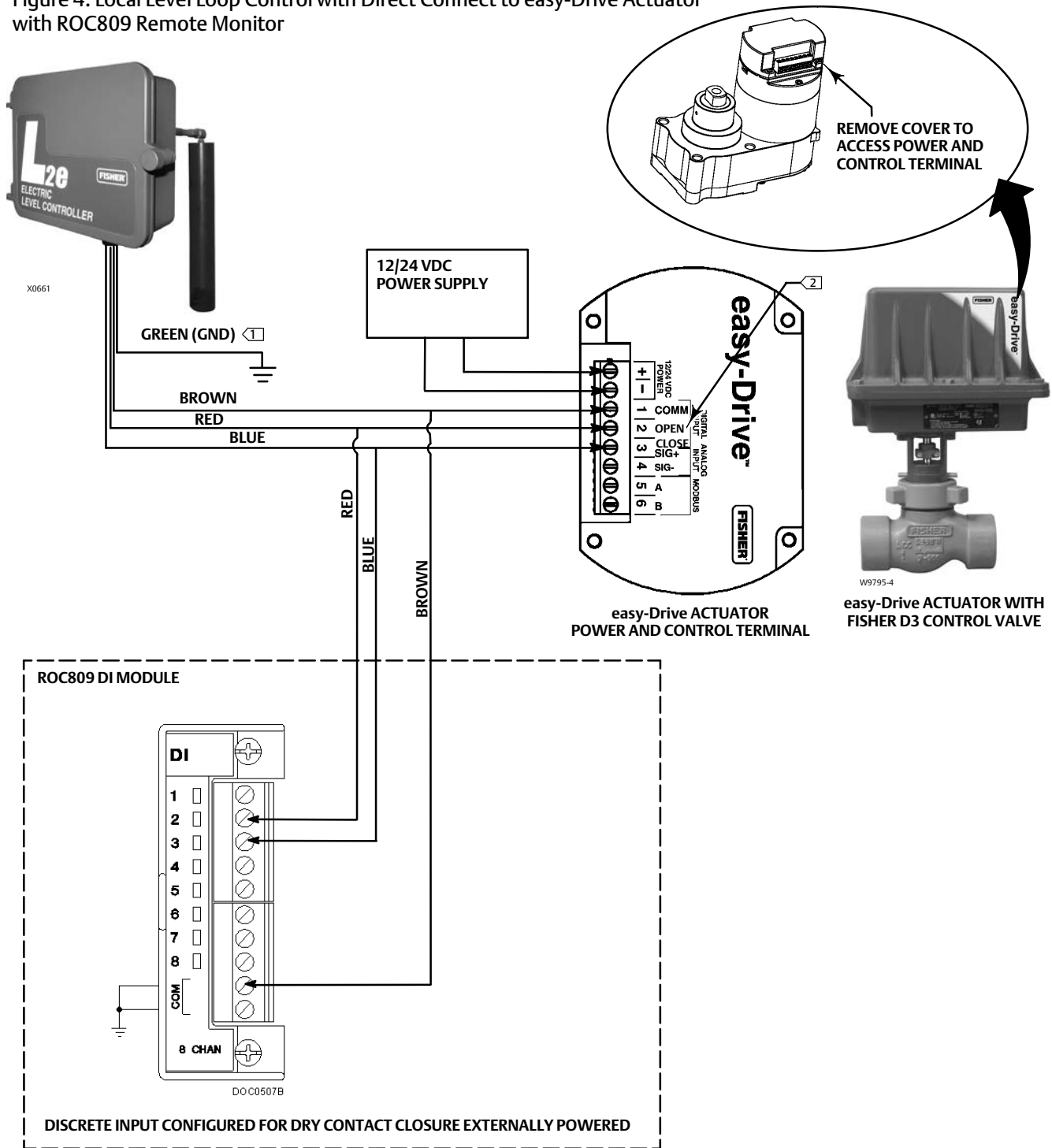
Use with easy-Drive electric actuator after first being used in other high power application is not recommended.

Figure 3. Local Level Control with Direct Connection to easy-Drive Actuator without Remote Monitor



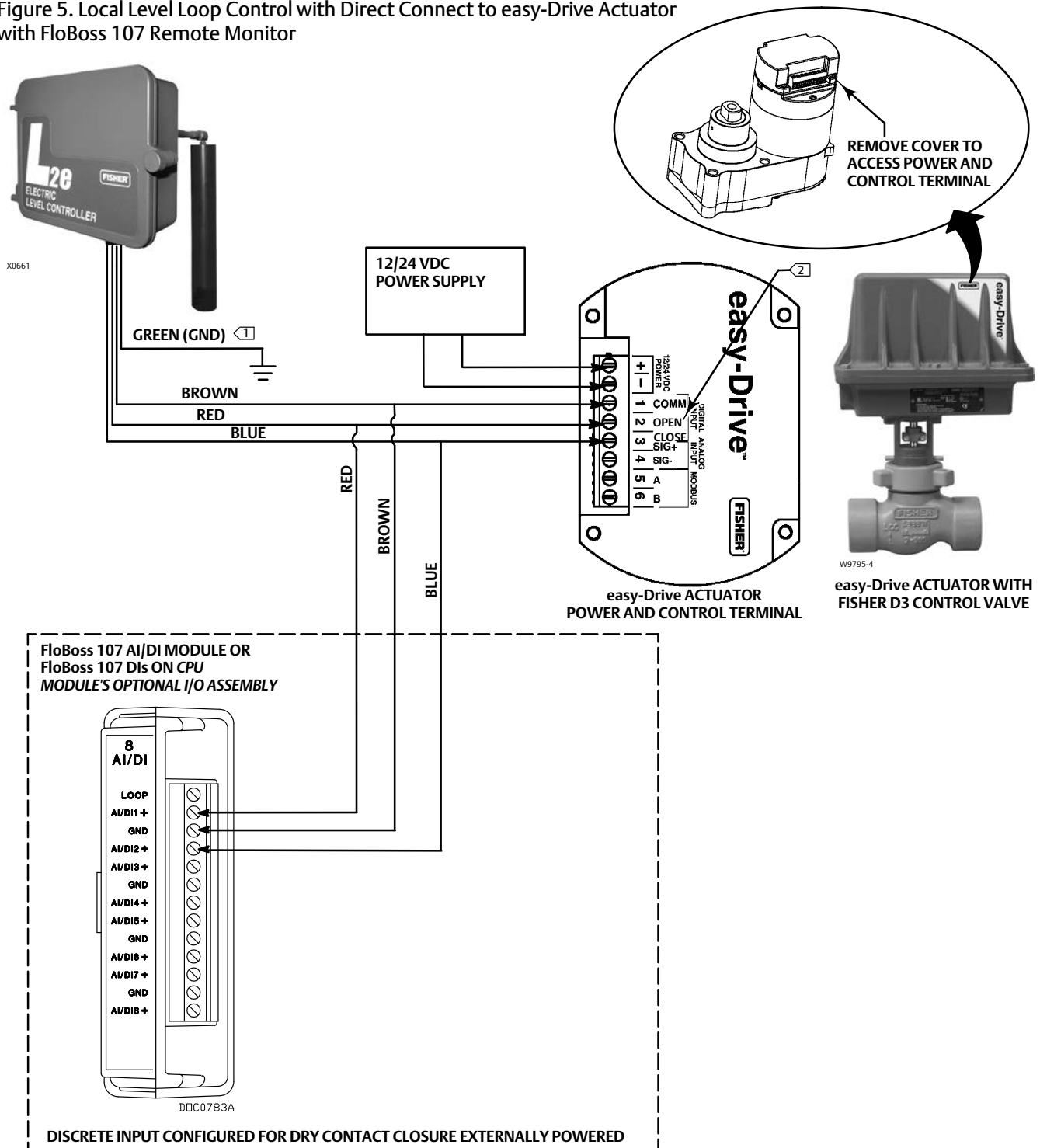
- ① CONNECT GREEN WIRE TO ACTUATOR GROUND (NOT SHOWN)
- ② OPEN CONTACT (2) MAY BE LABELED N.O. AND CLOSE CONTACT (3) MAY BE LABELED N.C.

Figure 4. Local Level Loop Control with Direct Connect to easy-Drive Actuator with ROC809 Remote Monitor



- ① CONNECT GREEN WIRE TO ACTUATOR GROUND (NOT SHOWN)
- ② OPEN CONTACT (2) MAY BE LABELED N.O. AND CLOSE CONTACT (3) MAY BE LABELED N.C.

Figure 5. Local Level Loop Control with Direct Connect to easy-Drive Actuator with FloBoss 107 Remote Monitor



- 1 CONNECT GREEN WIRE TO ACTUATOR GROUND (NOT SHOWN)
- 2 OPEN CONTACT (2) MAY BE LABELED N.O. AND CLOSE CONTACT (3) MAY BE LABELED N.C.

L2e Initial Setup (Dry Displacer)

Refer to figure 6.

1. Move Span to minimum setting.
2. Move Zero down until the valve opens, or N/C contact (red to brown leads) closes.
3. Slowly move Zero up until valve closes, or N/C contact (red to brown leads) opens.

L2e Zero and Span Adjustment (Wet Displacer)


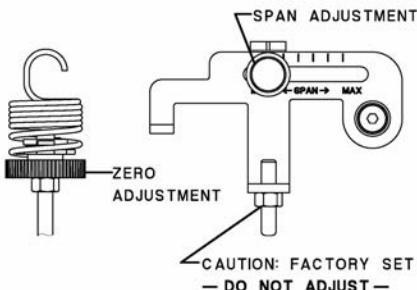
After initial setup (dry displacer) is complete,

1. Enable process flow into the vessel.
2. Move Zero and Span Adjustment for desired liquid zero position and level DG.
3. Tighten the Zero Adjustment hex nut (key 5), shown in figure 7, to lock the Zero setting.

Note

Scan the QR code shown in figure 6 or on the inside cover of the L2e for electric level loop field support.

Figure 6. Initial Setup

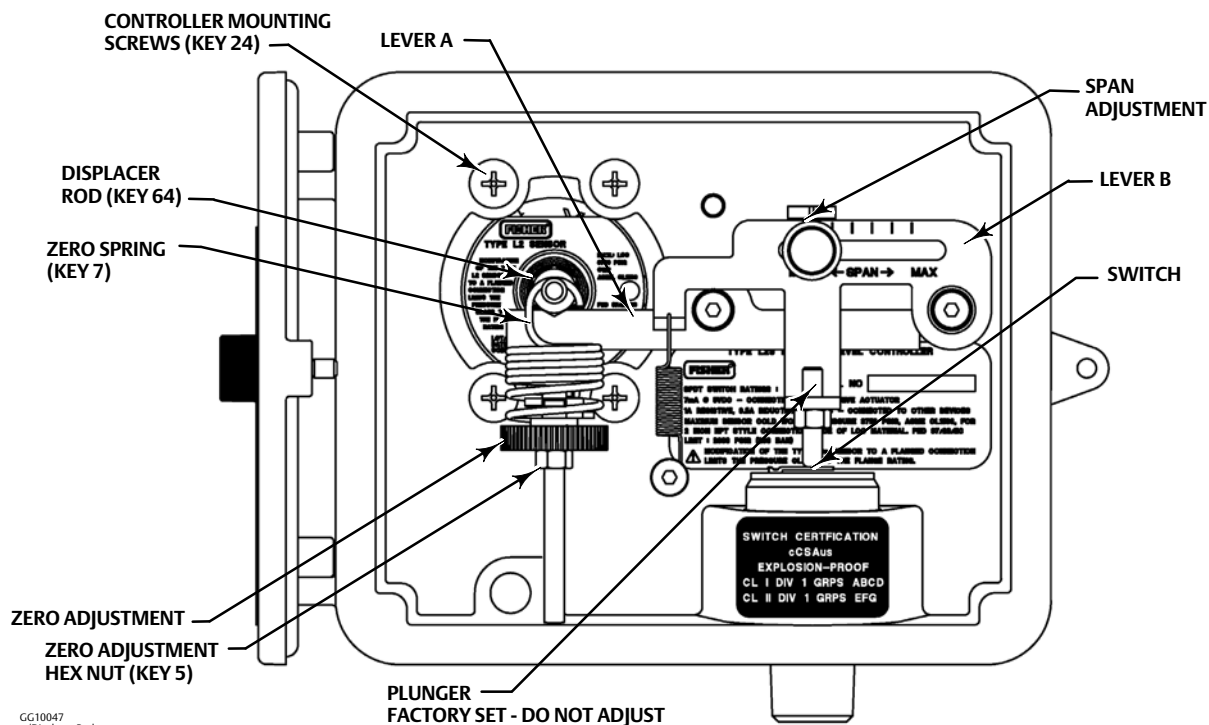
<p>INITIAL SETUP (DRY DISPLACER)</p> <ol style="list-style-type: none"> 1. MOVE SPAN TO MINIMUM SETTING (←). 2. MOVE ZERO DOWN UNTIL VALVE OPENS OR N/C CONTACT (RED TO BROWN LEADS) CLOSSES. 3. SLOWLY MOVE ZERO UP UNTIL VALVE CLOSSES OR N/C CONTACT (RED TO BROWN LEADS) OPENS. 		<p>SCAN FOR L2e AND easy-Drive FIELD SUPPORT</p> 																	
<p>ZERO AND SPAN ADJUSTMENT (WET DISPLACER)</p> <ol style="list-style-type: none"> 1. ENABLE PROCESS FLOW TO VESSEL. 2. MOVE SPAN AND ZERO FOR DESIRED CONTROL. 																			
		<table border="1"> <thead> <tr> <th></th> <th>MOVE</th> <th>LEVEL HEIGHT</th> </tr> </thead> <tbody> <tr> <td rowspan="2">ZERO ADJUSTMENT</td> <td>↑</td> <td>RAISE</td> </tr> <tr> <td>↓</td> <td>LOWER</td> </tr> <tr> <th colspan="3">LEVEL DIFFERENTIAL GAP</th> </tr> <tr> <td rowspan="2">SPAN ADJUSTMENT</td> <td>→</td> <td>INCREASE</td> </tr> <tr> <td>←</td> <td>DECREASE</td> </tr> </tbody> </table>			MOVE	LEVEL HEIGHT	ZERO ADJUSTMENT	↑	RAISE	↓	LOWER	LEVEL DIFFERENTIAL GAP			SPAN ADJUSTMENT	→	INCREASE	←	DECREASE
	MOVE	LEVEL HEIGHT																	
ZERO ADJUSTMENT	↑	RAISE																	
	↓	LOWER																	
LEVEL DIFFERENTIAL GAP																			
SPAN ADJUSTMENT	→	INCREASE																	
	←	DECREASE																	

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Principle of Operation

The operation of the L2e is based on Archimedes Principle, which states that a body immersed in a liquid will be buoyed up by a force equal to the weight displaced. The buoyant force and resultant movement of the displacer in the liquid is transmitted to the controller. As the buoyant force changes a proportional change in movement is seen by levers A and B (refer to figure 7). Levers A and B are arranged and connected by movable pivot or span adjustment so that the resultant movement between the plunger and the switch can be adjusted. For a given change in displacer movement the span adjustment will increase or decrease a proportional change in the plunger movement. As fluid level rises, the plunger moves away from the switch and vice versa.

Figure 7. Fisher L2e Controller



GG10047
w/Displacer Rod

Maintenance

Parts are subject to normal wear and must be inspected periodically and replaced as necessary. The frequency of parts inspection and replacement depends upon the severity of service conditions.

When inspection or repairs are required, disassemble only those parts necessary to accomplish the task.

⚠ WARNING

Always wear protective clothing, gloves, and eyewear when performing any maintenance operations to avoid personal injury. To avoid personal injury or property damage caused by the release of pressure or process fluid, observe the following before starting maintenance:

- Provide some temporary means of control for the process before taking the controller out of service.
- Provide a means of containing the process fluid before removing any measurement devices from the process.
- Vent any trapped process pressure.
- Check with your process or safety engineer for any additional measures that must be taken to protect against process media.

Removing the Controller From the Sensor

Refer to figure 7 for key number locations unless otherwise indicated.

1. Disconnect power from any electrical source.
2. Slide the hook end of the zero spring (key 7) over and off the controller end of the displacer rod (key 64).
3. Remove the four controller mounting screws (key 24), and pull the controller straight away from the sensor.

Installing Sensor Repair Kit (RL2SENSX012)

Refer to figure 9 for key number locations unless otherwise indicated.

Disassembly

1. Remove the controller from the sensor by following the procedure outlined in the previous section.
2. Remove the sensor from the vessel.
3. Unscrew the hex nut (key 67) and remove the spacer (key 66) and spring (key 68). After removing the spring, replace the spacer (key 66) and hex nut (key 67) on the displacer rod.

From the displacer end, pull the displacer rod away from the sensor connection (key 65) to pull the pivot base (key 73) loose from the sensor connection. Remove the hex nut (key 67) to permit removing the displacer rod, pivot base, pivot body, and spacer from the sensor connection.

4. Slide the pivot base (key 73), retaining ring (key 76), anti-extrusion ring (key 75), and O-ring (key 74) off the displacer rod. Remove the O-ring (key 77) and backup ring (key 78) from the pivot base.

Assembly

⚠ WARNING

Improper assembly of the O-rings, anti-extrusion ring, and backup ring could result in O-ring extrusion and permit leakage of process fluids. To avoid personal injury or property damage from leaking process fluid, be sure the O-rings, anti-extrusion ring and backup ring are assembled in the order shown in figure 9.

1. Place the pivot body (key 72) on the displacer rod (key 64) so that it is positioned as shown in figure 9.
2. Apply silicone sealant (key 79) to the O-ring (key 74) and slide onto the displacer rod assembly (key 64) with the anti-extrusion ring (key 75) and retaining ring (key 76). Be sure the O-ring, anti-extrusion ring, and retaining ring are in the order shown in figure 9. Slide the pivot base onto the displacer rod so that the knife edges of the pivot body (key 72) engage the slots in the pivot base (key 73).
3. Apply silicone sealant (key 79) to the O-ring (key 77) and install with the backup ring (key 78) into the groove on the pivot base (key 73). Be sure the backup ring is on the process pressure side of the O-ring as shown in figure 9.
4. Insert the displacer rod (key 64) into the vessel side of the sensor connection (key 65).
5. The pivot base must seat in the slots cast in the sensor connection. These slots will be horizontal when the sensor connection (key 65) is oriented as shown in figure 2.
6. To reduce the possibility of nicking the O-ring key (77) on the pivot base, keep the displacer rod centered in the sensor connection as much as possible while pushing the pivot base into the sensor connection. Be sure the pivot base seats in the slots cast in the sensor connection.
7. Slide the spring (key 68) and spacer (key 66) onto the displacer rod and secure with the hex nut (key 67). Fully tighten the hex nut (key 67).
8. Examine the sensor to ensure that the two pivot knife edges are seated in the pivot base slots.
9. Install the sensor on the vessel.

Replacing the Complete Controller Assembly (RL2E0X00C12)

Refer to figure 7 for key number locations unless otherwise indicated.

1. Disconnect power from any electrical source.
2. Slide the hook end of the zero spring (key 7) over and off the controller end of the displacer rod (key 64)
3. Remove the four controller mounting screws (key 24) and pull the controller straight away from the sensor.
4. Install the new controller assembly on the sensor.
5. Mount with the four screws (key 24).
6. Slide the hook end of the zero spring (key 7) on the controller end of the displacer rod (key 64).
7. Complete signal wiring hookup to easy-Drive electric actuator.
8. Perform the Initial Setup (Dry Displacer) and Zero and Span Adjustment procedures found on page 10.

Note

Use with easy-Drive electric actuator after first being used in other high power application is not recommended.

Related Documents

- [Bulletin 34.2:L2e Fisher L2e Electric Level Controller \(D103532X012\)](#)
- [Changing easy-Drive Electric Actuator On/Off Input Configuration from Single Dry Contact Control to Dual Dry Contact Control—Supplement to L2e Electric Level Controller Instruction Manual \(D103987X012\)](#)
- [Converting a Threaded NPT Connection to a Flange Connection—Supplement to Fisher L2 and L2sj Liquid Level Controller Instruction Manuals \(D103277X012\)](#)
- [Dimensions for NPS 2 CL150 through 1500 Slip On Flange Connections—Supplement to Fisher L2 and L2sj Liquid Level Controller Instruction Manuals \(D103405X012\)](#)
- [Bulletin 51.2:D3 Fisher D3 Control Valve \(D103269X012\)](#)
- [Fisher D3 Control Valve with easy-Drive Electric Actuator Instruction Manual \(D103460X012\)](#)
- [Bulletin 51.2:D4 Fisher D4 Control Valve Assembly \(D103039X012\)](#)
- [Fisher D4 Control Valve with easy-Drive Electric Actuator Instruction Manual \(D103597X012\)](#)

All documents are available from your [Emerson Process Management sales office](#). Also visit our website at www.Fisher.com.

Parts Ordering

When corresponding with your Emerson Process Management sales office about this equipment, always mention the serial number of the controller. The serial number can be found on the nameplate.

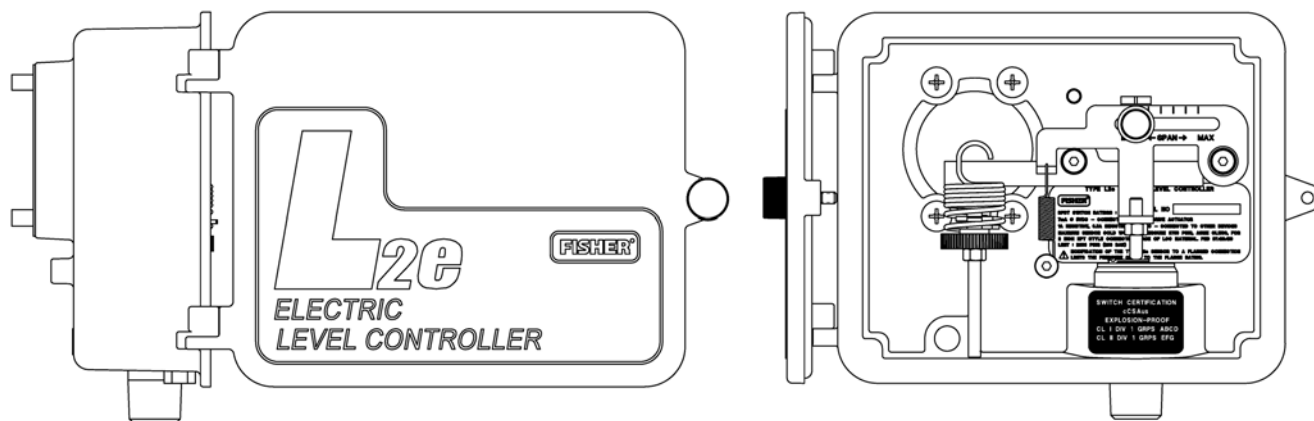
⚠ WARNING

Use only genuine Fisher replacement parts. Components that are not supplied by Emerson Process Management should not, under any circumstances, be used in any Fisher instrument. Use of components not supplied by Emerson Process Management may void your warranty, might adversely affect the performance of the valve, and could cause personal injury or property damage.

Kits

Description	Part Number	Description	Part Number
Sensor Repair Kit Repair kit includes keys 74, 75, 76, 77, and 78 (fluorocarbon O-rings, anti-extrusion ring, retaining ring, and fluorocarbon backup ring)	RL2SENSX012	Controller Assembly Replacement Replacement kit includes complete controller assembly (figure 8) with mounting screws and gasket	RL2E0X00C12

Figure 8. Fisher L2e Electric Level Controller Assembly



GG10047-E

Parts List

Key Description

Note

Contact your [Emerson Process Management sales office](#) for Part Ordering information.

Sensor (see figure 9)

63	Hex jam nut, 316 SST
64	Displacer rod, 17-4 SST (17-4PH SST)
65	Sensor connection
66	Spacer, 304 SST
67	Hex jam nut, 316 SST
68	Conical spring, 316 SST
69	Universal Joint, 316 SST (vertical displacer only)
70	Nameplate
71	Drive screw, stainless steel
72	Knife pivot body, CB7CU-1 (17-4PH SST)
73	Knife pivot base, CF8M (316 SST)

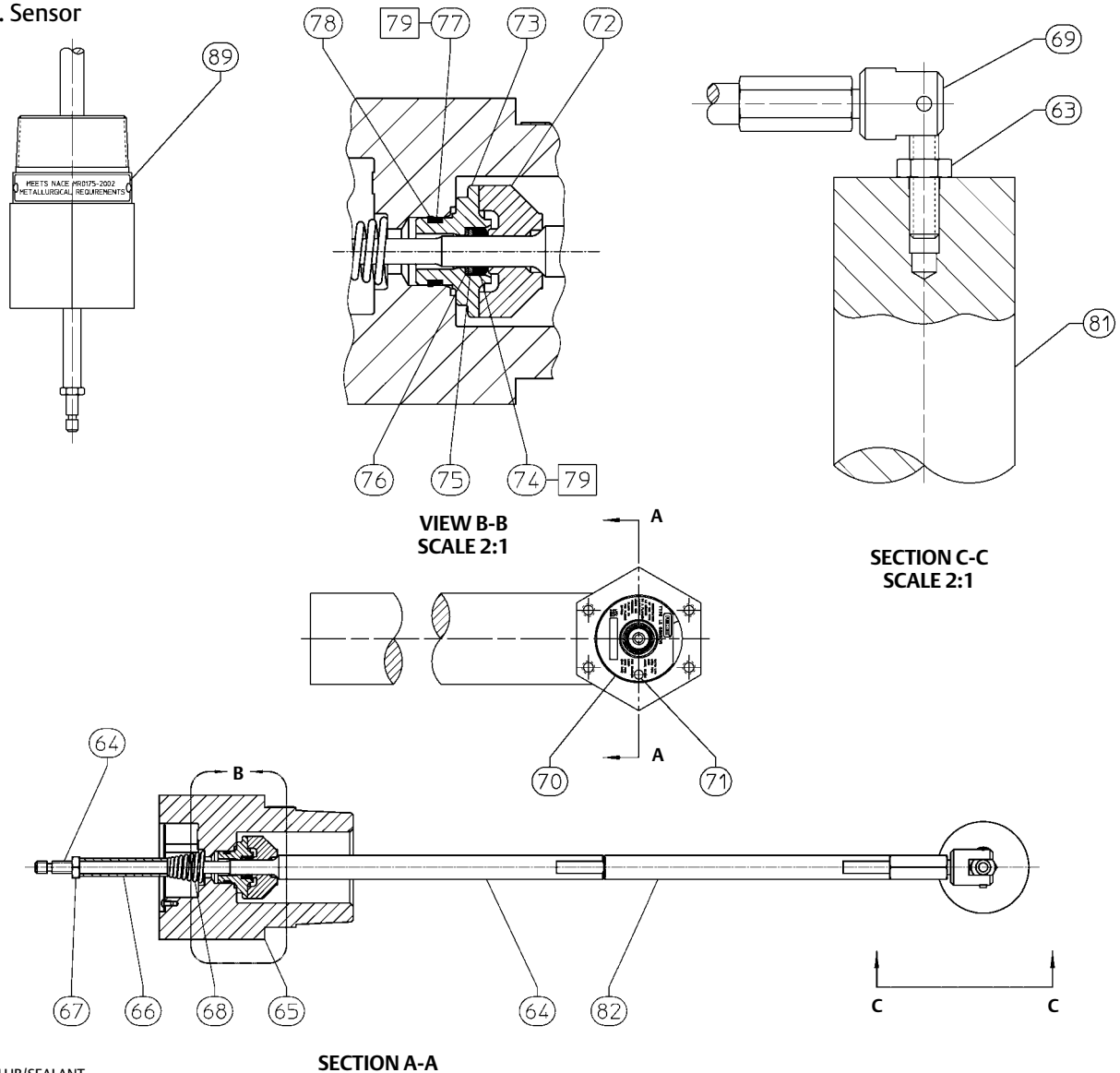
Key Description

Note

Keys 74, 75, 76, 77, and 78 are included in the Sensor Repair Kit.

74	O-Ring, fluorocarbon
75	Anti-extrusion ring, PTFE
76	Retaining ring, 304 SST
77	O-Ring fluorocarbon
78	Backup ring, fluorocarbon
79	Sealant, silicone (not furnished with sensor)
81	Displacer, 1-7/8x12-inches PVC S31603 3x6-inches PVC
82	Extension 3 inches 6 inches
89	NACE Label

Figure 9. Sensor



□ APPLY LUB/SEALANT
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Emerson Process Management
Marshalltown, Iowa 50158 USA
Sorocaba, 18087 Brazil
Cernay, 68700 France
Dubai, United Arab Emirates
Singapore 128461 Singapore

www.Fisher.com

